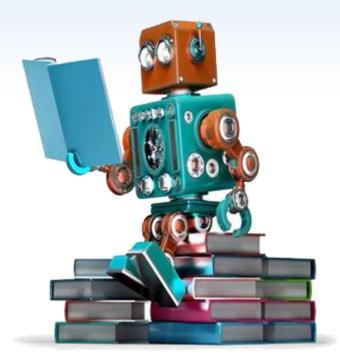


机器学习与人工智能

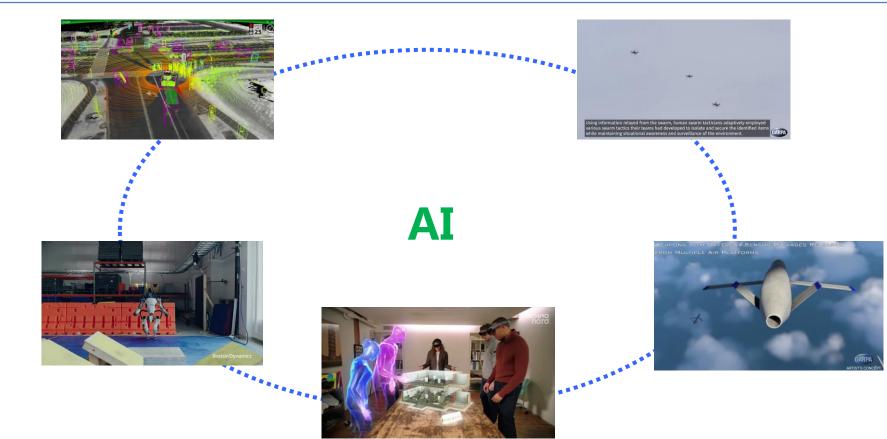
布树辉

https://gitee.com/pi-lab/machinelearning_notebook













- Small, cheap
- No pilot
- Convenient
- Strong survivability

- Aerial photograph
- Attack
- Air platformGeneral aviation











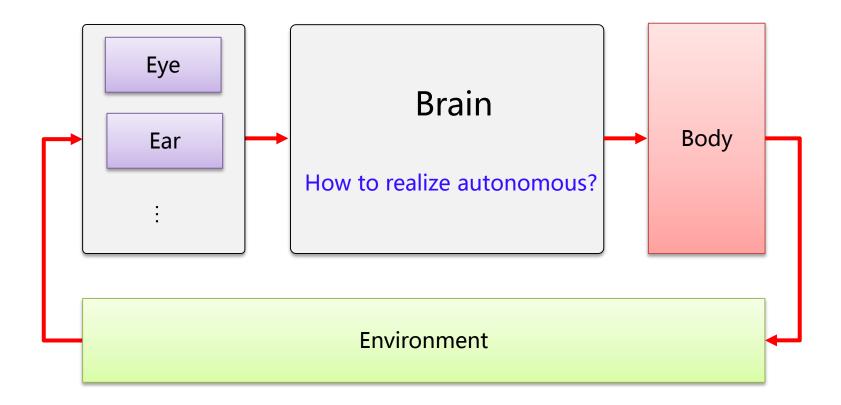




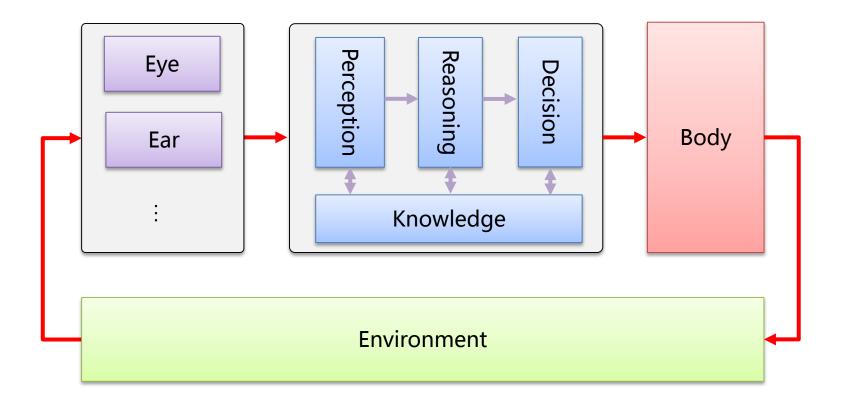












New Challenges





- Multi-type sensors: IMU, GPS, Image, LiDAR, RADAR ...
- High quality and real-time speed required
- Reasoning and knowledge are important for realizing strong AI

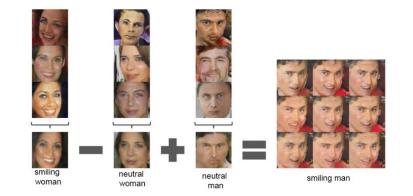










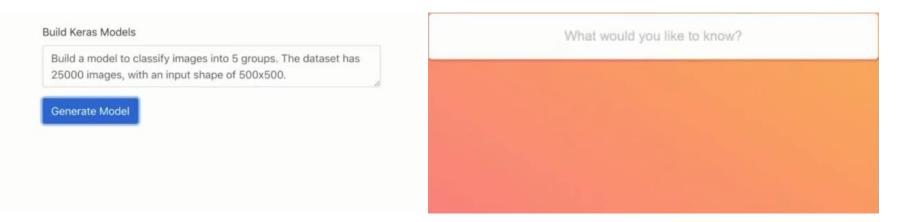




input



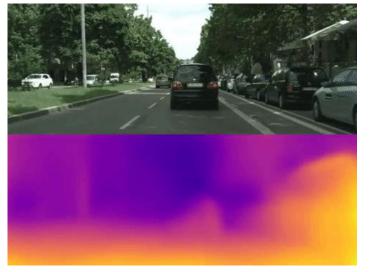


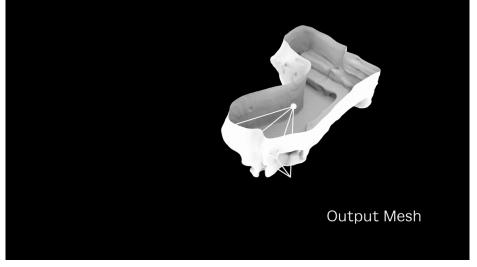


GPT-3 Automatic Keras Model

GPT-3 Automatic SQL





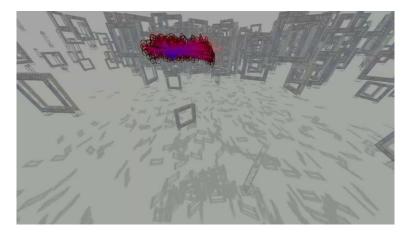


Deep Leraning based SLAM

Deep Leraning based 3D Reconstruction



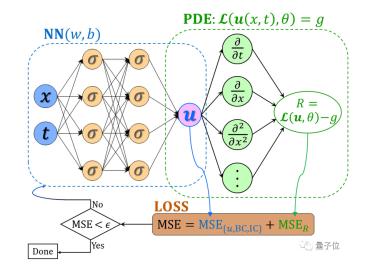


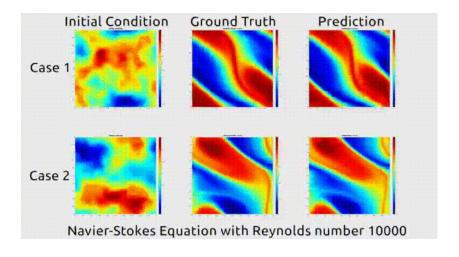


Robot Control

UAV Cluster Control







Flow Estimation



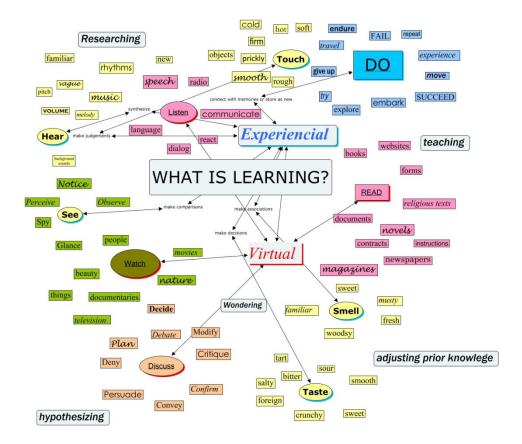




How to Achieve Intelligence?

How to Achieve Intelligence?





Learning is about seeking a predictive and/or executable understanding of natural/artificial subjects phenomena or activities from ...



Machine learning seeks to develop theories and computer systems for

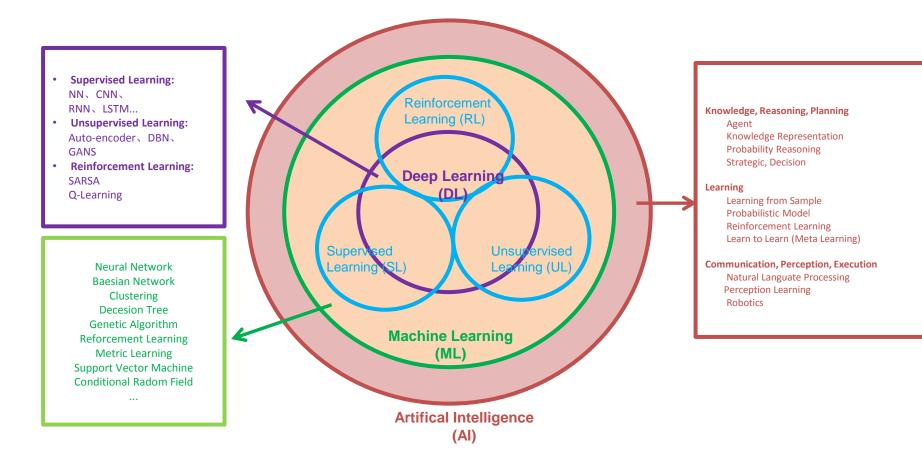
- Representing
- Classifying, clustering, recognizing
- Reasoning under uncertainty
- Predicting
- And reacting to
- ...

Complex, real world data, based on the system's own experience with data, and (hopefully) under a unified model or mathematical framework, that

- Can be formally characterized and analyzed
- Can take into account human prior knowledge
- Can generalize and adapt across data and domains
- Can operate automatically and autonomously
- And can be interpreted and perceived by human

Machine Learning and AI









"A pattern is the opposite of a chaos; it is an entity vaguely defined, that could be given a name."

- Watanabe







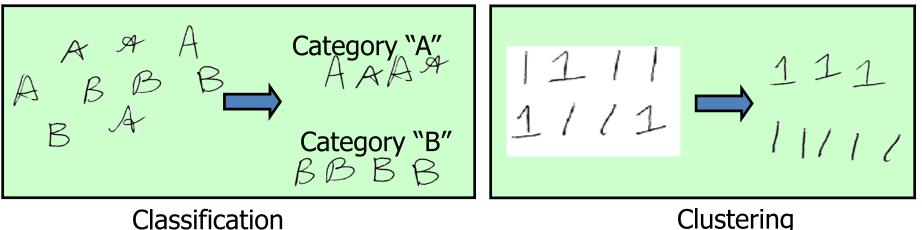


Recognition



Identification of a pattern as a member of a category we already know, or we are familiar with

- Classification (known categories)
- **Clustering** (learning categories)

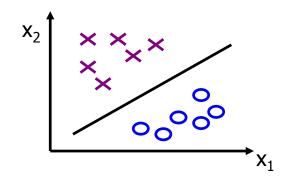


Classification

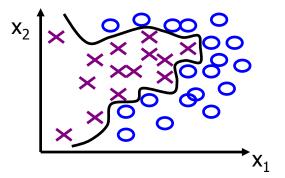
Representation



- Each pattern is represented as a point in *d*-dimensional feature space
- Choice of features and their desired invariance properties are domainspecific



- Good representation implies
 - small intra-class variation
 - large inter-class separation
 - simple decision boundary



Intra-class Variability





The letter "T" in different typefaces

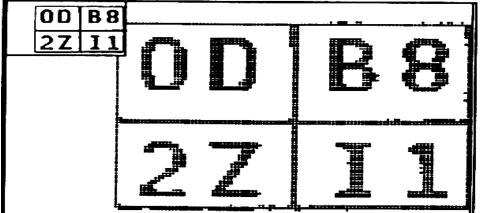


Same face under different expression, pose, illumination

Inter-class Similarity







Identical twins

Characters that look similar

Inter-class or Intra-class?







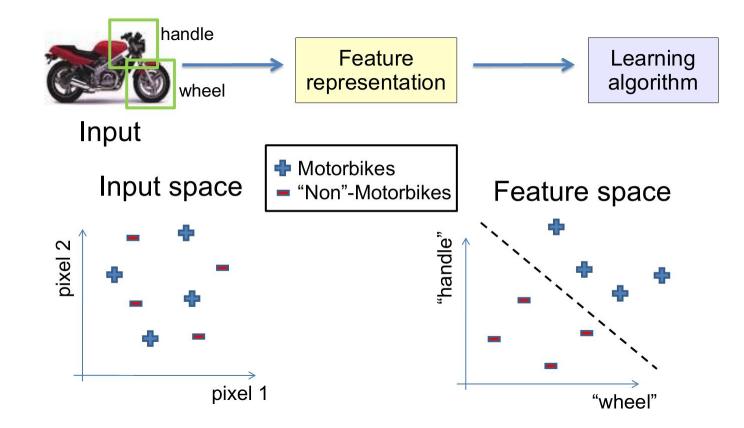


Good Representation

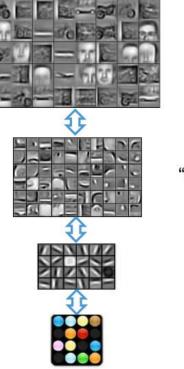
- Should have some invariant properties (e.g., rotation, translation, scale, ...)
- Account for intra-class variations
- Ability to discriminate pattern classes of interest
- Robustness to noise, occlusion,...
- Lead to simple decision making strategies (e.g., linear decision boundary)
- Low measurement cost; real-time

Good Representation









3rd layer "Objects"

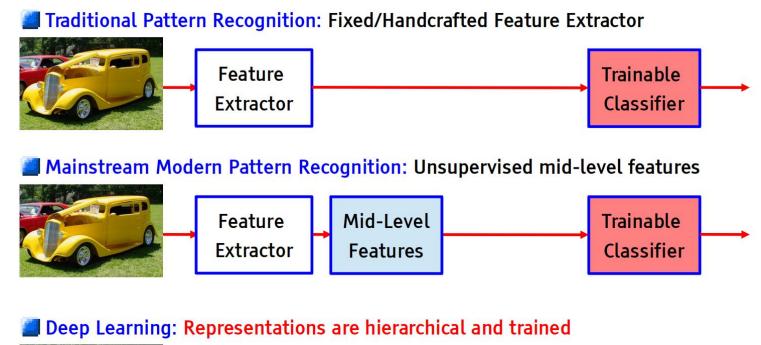
2nd layer "Object parts"

> 1st layer "edges"

> > Input

- Represent objects from lowlevel to high-level structure
- Can share the low-level representation for multiple tasks

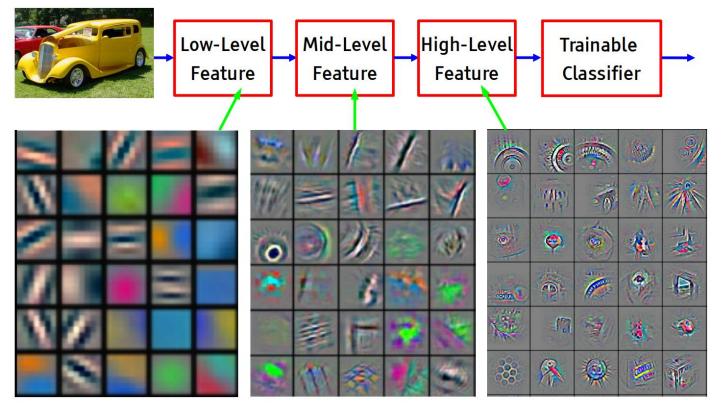








It's deep if it has more than one stage of non-linear feature transformation

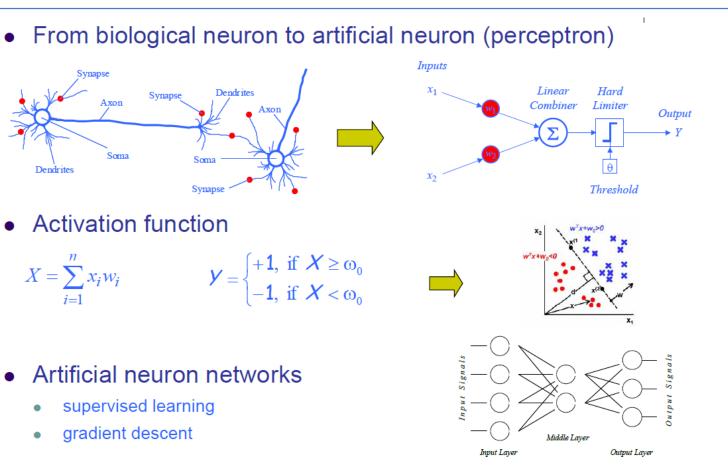




Neural Networks and Deep Learning

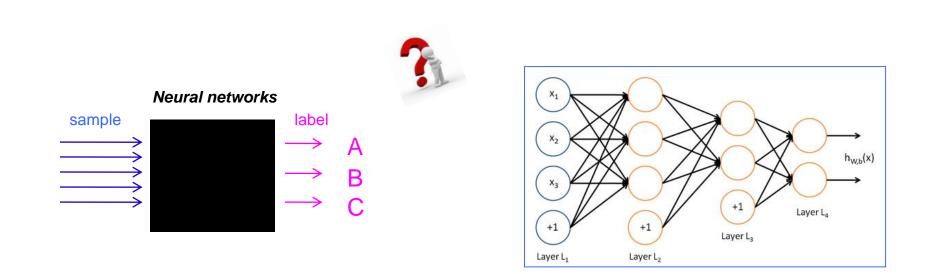
Perceptron and Neural Networks





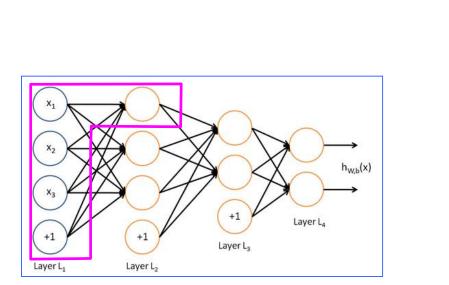
Neural Networks

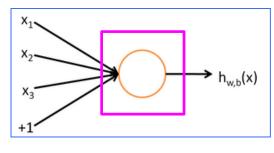


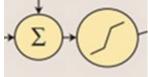


Neural Networks - Feedforward Networks







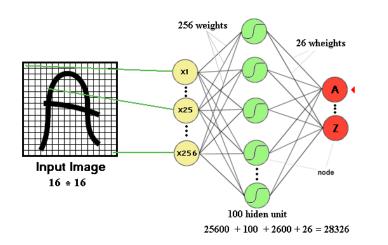


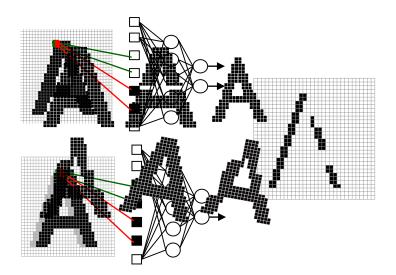
$$h_{W,b}(x) = f(W^T x) = f(\sum_{i=1}^3 W_i x_i + b)$$
$$f(z) = \frac{1}{1 + \exp(-z)}$$

www.cybercontrols.org



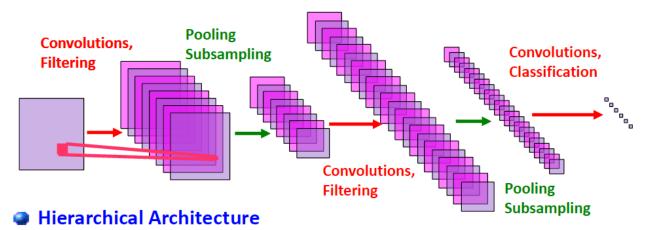
- The number of trainable parameters becomes extremely large
- Little or no invariance to shifting, scaling, and other forms of distortion





Convolutional Neural Network: Multi-stage Trainable Architecture





Representations are more global, more invariant, and more abstract as we go up the layers

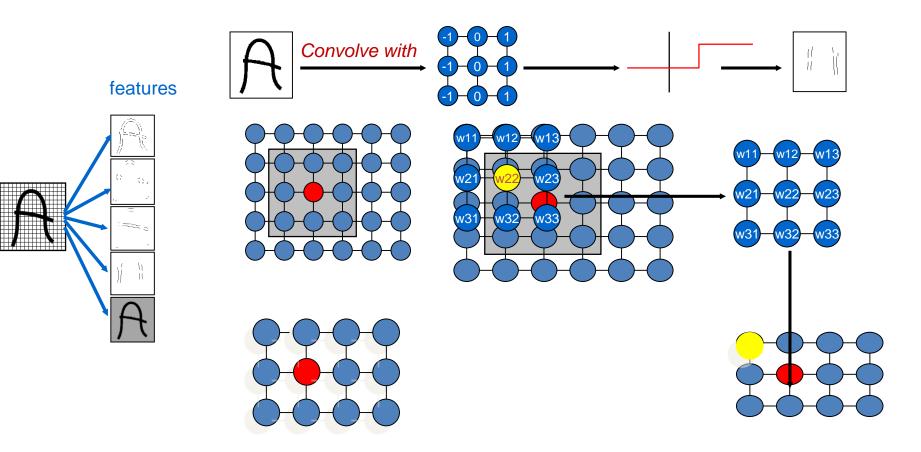
Alternated Layers of Filtering and Spatial Pooling

- Filtering detects conjunctions of features
- Pooling computes local disjunctions of features

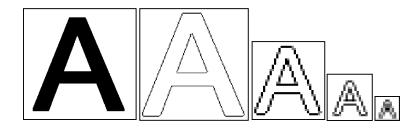
Fully Trainable

All the layers are trainable

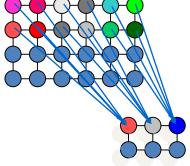




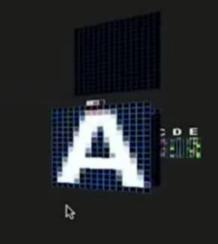






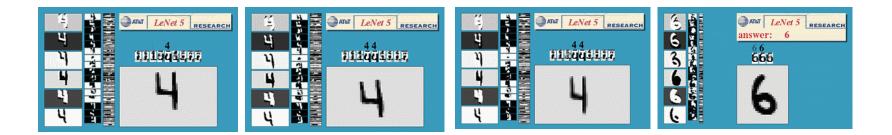


- By reducing the spatial resolution of the feature map, reduce the effect of noises and shift or distortion.
- The weight sharing is also applied in subsampling layers







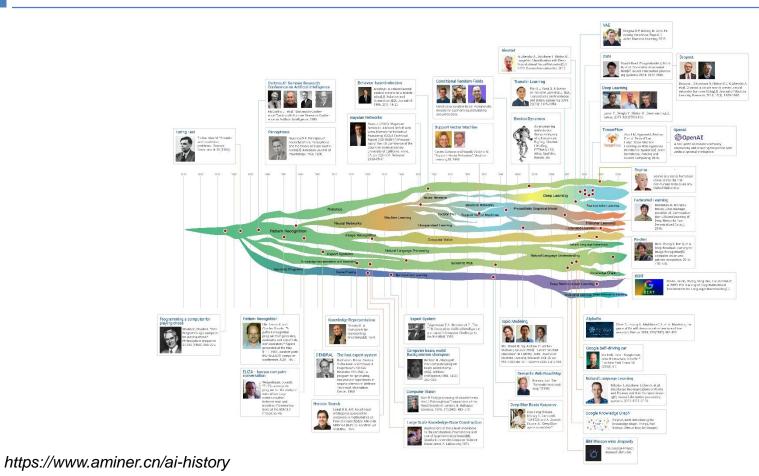




Summary

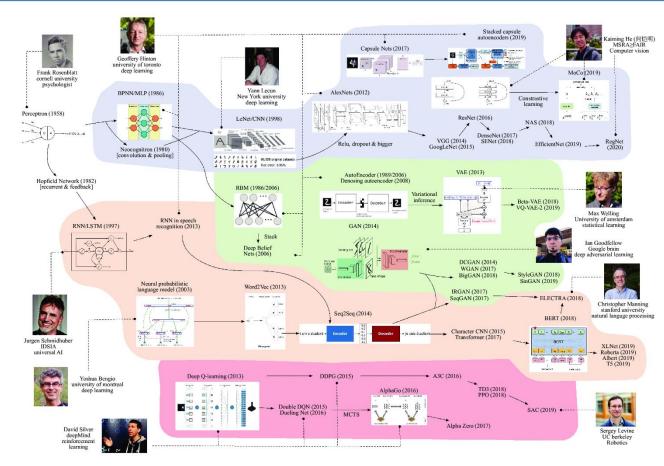
Summary - History of AI





Summary - Methods



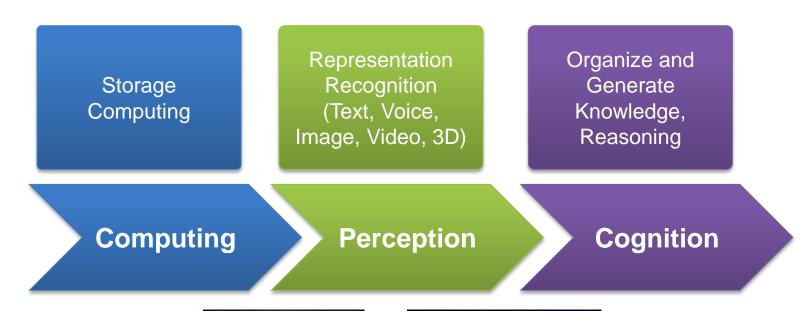


Summary - Problems



- General-purpose intelligent system is a very difficult problem
- Successful systems available in well-constrained domains
- All components are coupled
- No single approach has been found to be optimal for all problems
- Use of object models, constraints and context is necessary for identifying complex patterns
- Careful sensor design and feature extraction often lead to simple models









Books





http://www.adv-ci.com/blog/mlai

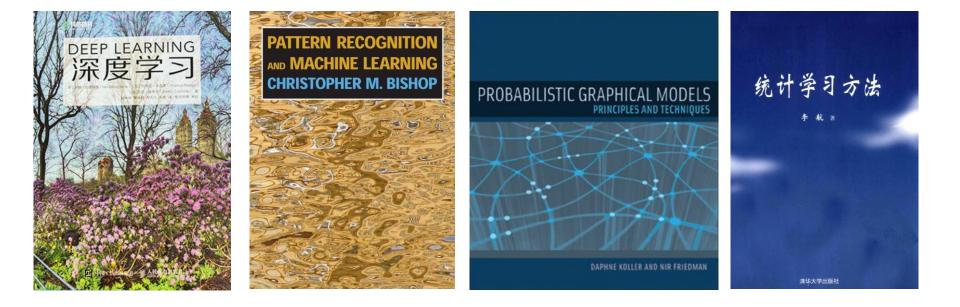
以机器学习的算法原理与实现贯穿始终, 通过算法、数据结构、面向对象、编程实 现一步一步地引入

让读者无需额外学习算法与数据结构等知识,就能理 解并应用机器学习到各自的专业。



Other Books





Materials



Notebook: <u>https://gitee.com/pi-lab/machinelearning_notebook</u> Homework: <u>https://gitee.com/pi-lab/machinelearning_homework</u> Video: <u>https://www.bilibili.com/video/BV1oZ4y1N7ei</u>





THANK YOU

CR.P.

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